

01/23/06 Fundamentals of Probability Theory

Homework 1 posted due February 6 (Monday)

Probability space: Ω

Discrete: coin flips

terrorist status (yes/no) in some population

Can you see me now?

Continuous: location of particle (\mathbb{R}^3)

Abstract: Financial markets over the next year

Status of New Orleans after an Atlantic hurricane

Elements $\omega \in \Omega$ describe complete information for one possible outcome

An "event" A is a set of possible outcomes $A \subseteq \Omega$

$$\text{Prob}(A) = \sum_{\omega \in A} \text{Prob}(\omega) \quad \text{for discrete state spaces}$$

The $\text{Prob}(\omega)$ must be specified by model,

"Prob" behaves like a positive measure,

$$\text{Prob}(A \cup B) = \text{Prob}(A) + \text{Prob}(B)$$

" if the events
A or B A and B are mutually exclusive
($A \cap B = \emptyset$)

$$\text{Prob}(A) \geq 0$$

$$\text{Prob}(\emptyset) = 0$$

$$\text{Prob}(\Omega) = 1$$

$$\text{Prob}(\Omega \setminus A) = \text{Prob}(\Omega) - \text{Prob}(A)$$

$$\text{Prob}(\text{not } A) = 1 - \text{Prob}(A)$$

Technically the probability measure

"Prob" may only be defined for some collection of subsets of Ω .

- important for continuous and abstract prob spaces.

In dependence: ~~Events A and B~~
~~have no~~ ~~connection~~

Two events A, B are independent if the outcome of A happening or not happening has no connection to whether B happens.

$$\text{Prob}(A \text{ and } B) = \text{Prob}(A) \text{Prob}(B)$$

||

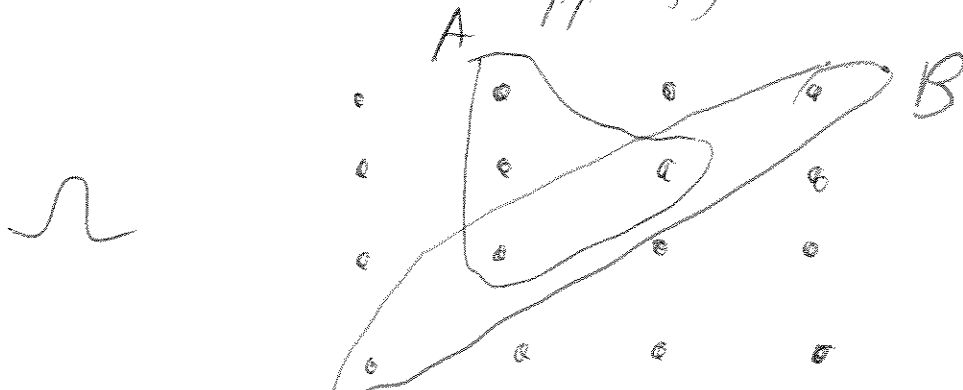
$$\text{Prob}(A \cap B)$$

More general notion of connection of two events

Conditional probability:

$$\text{Prob}(A | B) = \frac{\text{Prob}(A \text{ and } B)}{\text{Prob}(B)}$$

Prob(A happens, given that B happens) (true in general)



If uniform probability,

$$\text{Prob}(A) = 1/4$$

$$\text{Prob}(B) = 1/4$$

$$\text{Prob}(A \text{ and } B) = \frac{1}{8}$$

$$\text{Prob}(\text{~~B~~ } A | B) = \frac{\frac{1}{8}}{1/4} = 1/2$$

Statistical independence

$$\Leftrightarrow \text{Prob}(A | B) = \text{Prob}(A)$$

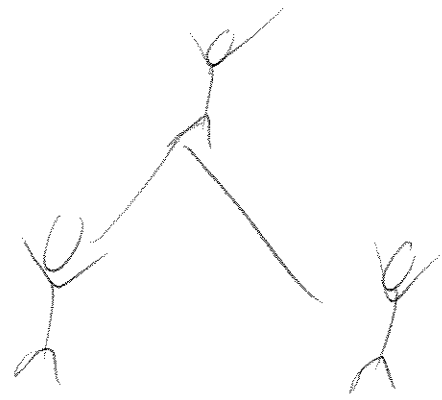
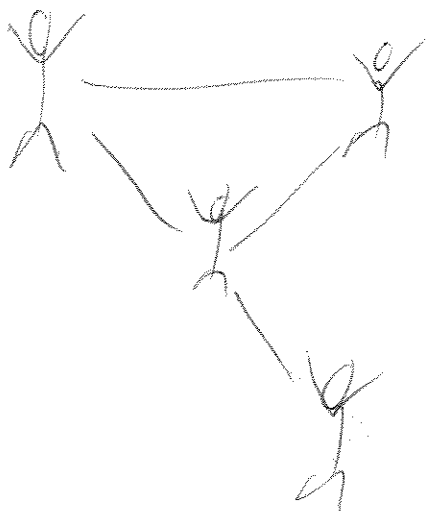
if A, B independent.

Probability

Random variables are "measurable" functions on probability space.

The range of a random variable is called the state space.

Measurable means, for random variables \underline{X} with discrete state space, that $\text{Prob}(\underline{X} = x)$ is well defined for any value $x \in S$ (state space)



More formally:

$$\underline{X}: \Omega \rightarrow S$$

$$\text{Prob}(\underline{X} = x) = \sum_{\substack{w \in \Omega: \\ \underline{X}(w) = x}} \text{Prob}(w)$$

To be a little more precise, we make the probability measures on the various spaces more precise:

$$\text{For } A \subseteq \Omega \quad \text{Prob}(A) \equiv P(A)$$

$$\text{For } B \subseteq S \quad \text{Prob}(B) = P_{\underline{X}}(B)$$

$$P_{\underline{X}}(B) = \sum_{\substack{w \in \Omega: \\ \underline{X}(w) \in B}} P(w) = \sum_{w \in \underline{X}^{-1}(B)} P(\{w\})$$

$P_{\underline{X}}$ is a measure induced on S by pushing forward the measure P on Ω through the function $\underline{X}: \Omega \rightarrow S$

① P is a measure defined on some "measurable" collection of subsets of Ω .

For discrete state spaces, a practical way to work is to define:

$$P_x = P_{\underline{X}}(\{x\}) = \text{Prob}(\underline{X} = x)$$

$$P_{\underline{X}}(B) = \sum_{x \in B} P_x$$

This allows one to work with the set of positive reals

$\{P_x\}_{x \in S}$ rather than measures

Practical info about random variable \underline{X} (discrete state space still)

Probability distribution: $\{P_x\}_{x \in S}$

- complete statistical info about \underline{X}

Useful condensations of info about \underline{X} :

Mean (average or expected value):

$$\begin{aligned}\mu_{\underline{X}} &= \langle \underline{X} \rangle = \mathbb{E} \underline{X} \\ &= \sum_{x \in S} x p_x\end{aligned}$$

More generally for any function f defined on S

$$\langle f(\underline{X}) \rangle = \sum_{x \in S} f(x) p_x$$

Average/expected value of $f(\underline{X})$

Variance:

$$\sigma_{\underline{X}}^2 = \langle (\underline{X} - \mu_{\underline{X}})^2 \rangle$$

reflects how much \underline{X} tends to deviate from mean value.

Simple rules for manipulating

$\langle \cdot \rangle$: behave like sums + integrals

~~For example, can formally view:~~

This is a linear operation:

$$\langle a f(\mathbb{X}) + b g(\mathbb{X}) \rangle$$

$$= a \langle f(\mathbb{X}) \rangle + b \langle g(\mathbb{X}) \rangle$$

for $a, b \in \mathbb{C}$ (deterministic)

~~Can also~~

Parameters which are not random
behave like parameters independent
of integration variable.

- can factor out of integral.

$$\int y x^2 dx = y \int x^2 dx$$

Example calculation:

$$\sigma_{\mathbb{X}}^2 = \langle (\mathbb{X} - \mu_{\mathbb{X}})^2 \rangle$$

$$= \langle \mathbb{X}^2 - 2\mu_{\mathbb{X}}\mathbb{X} + \mu_{\mathbb{X}}^2 \rangle$$

$$= \langle \mathbb{X}^2 \rangle - 2\mu_{\mathbb{X}} \langle \mathbb{X} \rangle + \mu_{\mathbb{X}}^2 \langle 1 \rangle$$

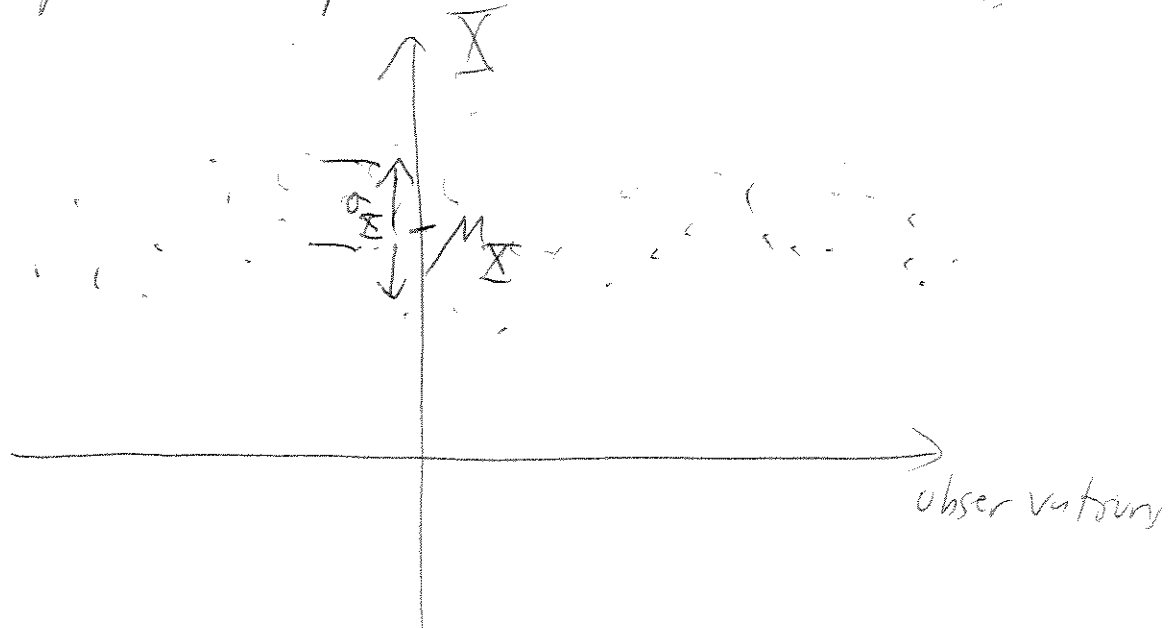
because $\mu_{\mathbb{X}}$ is not random,

$$= \langle \bar{X}^2 \rangle - 2\mu_{\bar{X}}^2 + \mu_{\bar{X}}^2$$

$$\sigma_{\bar{X}}^2 = \langle \bar{X}^2 \rangle - \mu_{\bar{X}}^2$$

Standard deviation: $\sigma_{\bar{X}} = \sqrt{\sigma_{\bar{X}}^2}$

- typical departure from mean.

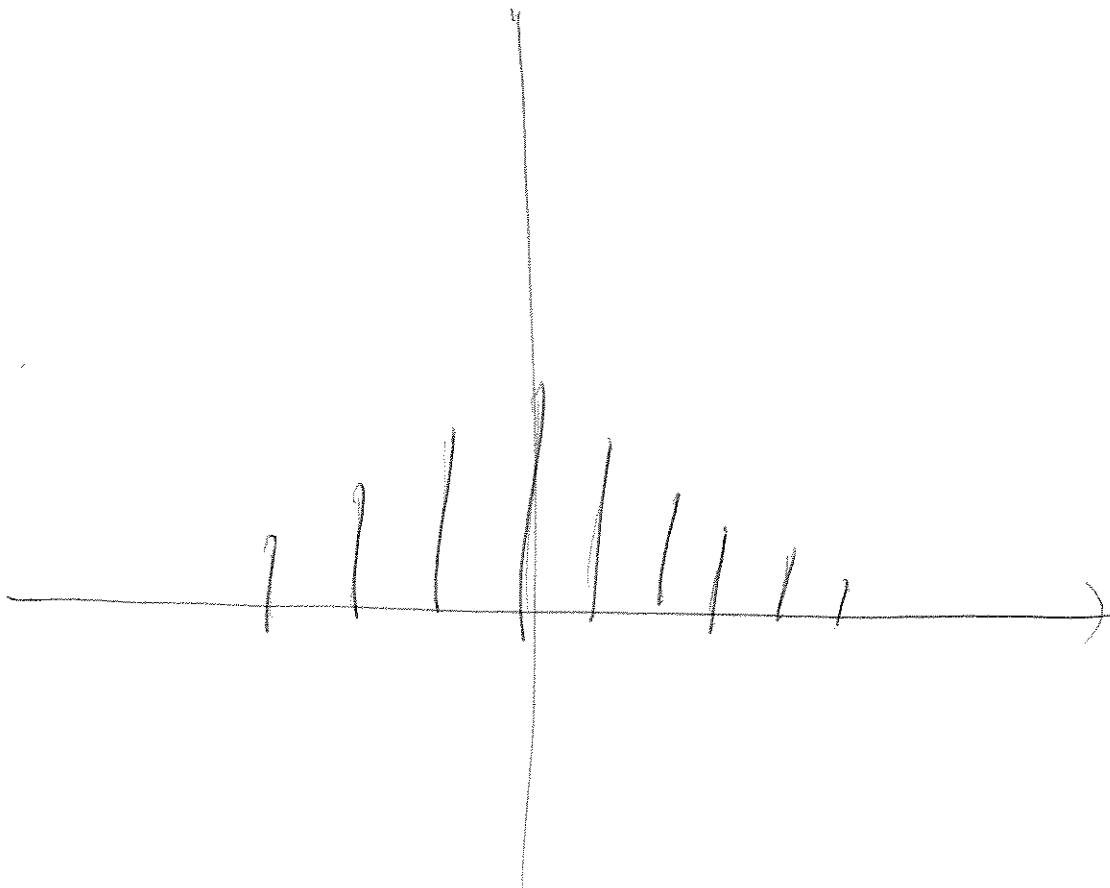
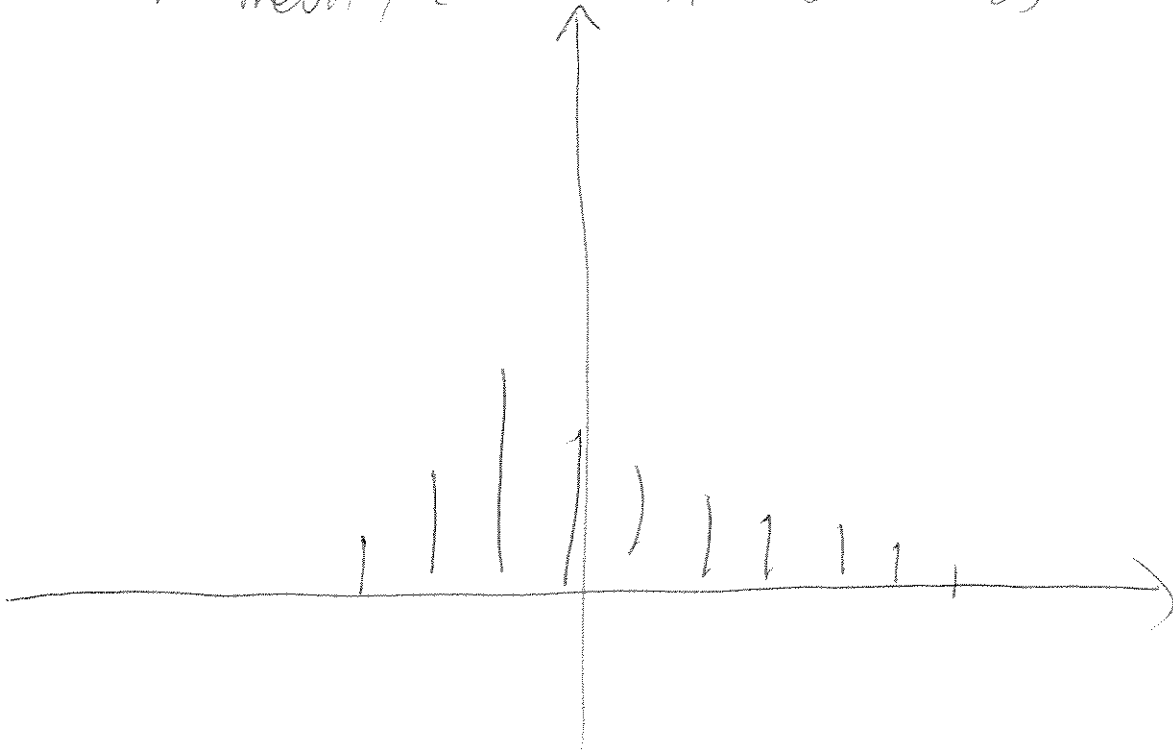


Further information about random variables from higher moments

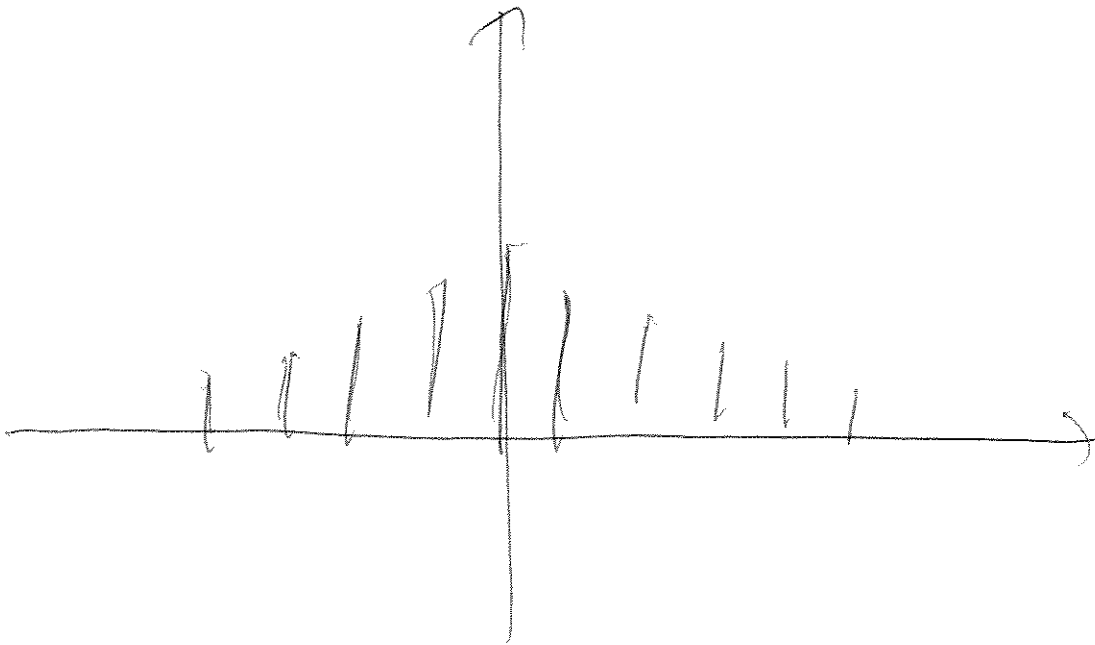
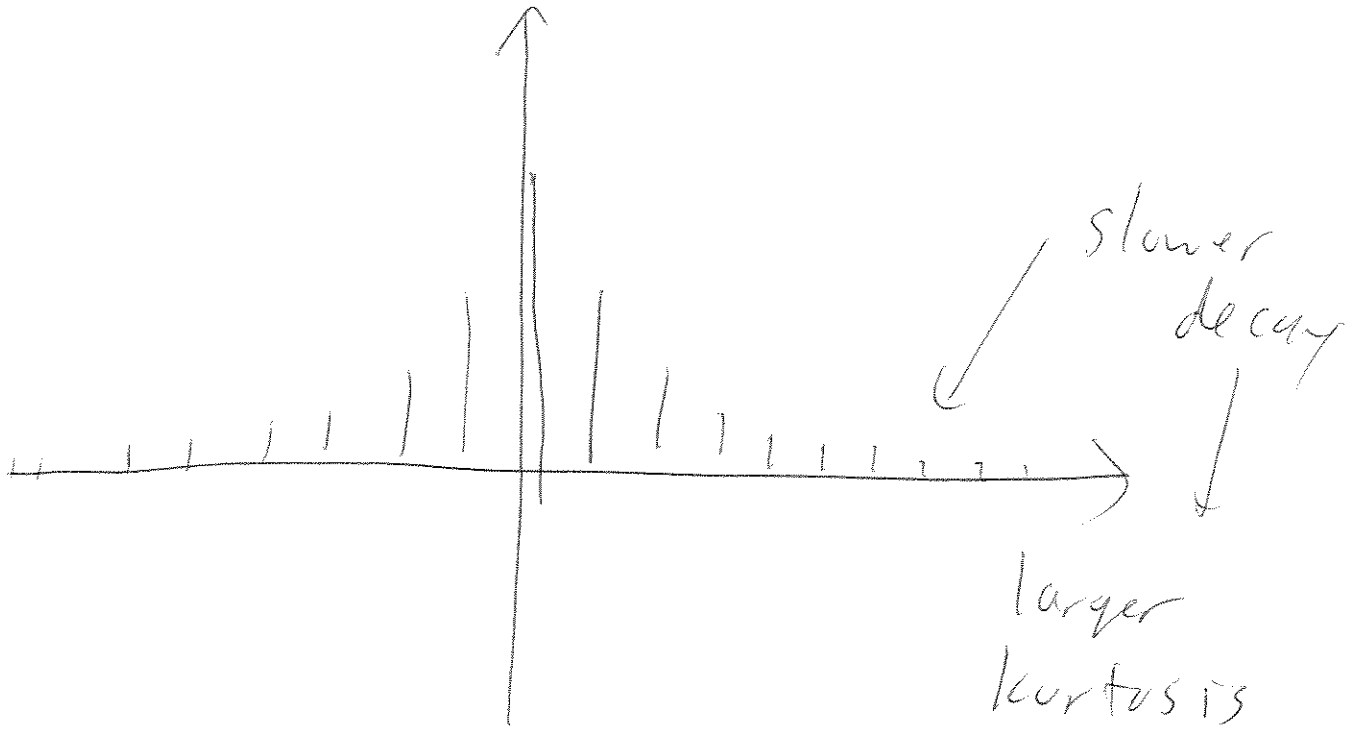
$$\langle \bar{X}^n \rangle = \sum_{x \in S} x^n p_x \quad \text{for } n = 1, 2, 3, \dots$$

Actually "cumulants" are better way to organize information.
- modified moments

Third moment / cumulant: skewness



Fourth moment/cumulant: kurtosis
flatness factor
- rapidness of decay in tails



Examples of random variables
with discrete state space:

1) Binomial distribution

$$S = \{0, 1, 2, \dots, N\}$$

$$\text{Prob}(\underline{X} = j) = \binom{N}{j} p^j (1-p)^{N-j}$$

where p is a prescribed
value $0 < p < 1$.

$$\binom{N}{j} = {}_N C_j = \frac{N!}{(N-j)! j!}$$

Interpretation: Bernoulli trials
(coin flips)

- N independent trials
- p = probability of positive outcome
in any given trial.

\underline{X} = # positive outcomes in
 N trials.

2) Uniform distribution

$$S = \{0, 1, \dots, N\}$$

$$\text{Prob}(X = j) = \frac{1}{N+1} \text{ for } 0 \leq j \leq N.$$

Equal likelihood for each
outcome,

Office hours

Wed 3-4 PM

Fri 4-5 PM