

04/19/04

For the opposite extreme of pure diffusion:

$$v \equiv 0 \quad (\text{no drift})$$

$$K = \frac{1}{2} \mathbb{1} \quad (\text{pure constant diffusion})$$

← identity matrix

Backward equation:

$$-\frac{\partial u}{\partial s} = \frac{1}{2} \Delta u$$

$$\Delta = \frac{\partial^2}{\partial x_1^2} + \dots + \frac{\partial^2}{\partial x_d^2}$$

$$u(\vec{x}, s=t) = f(\vec{x})$$

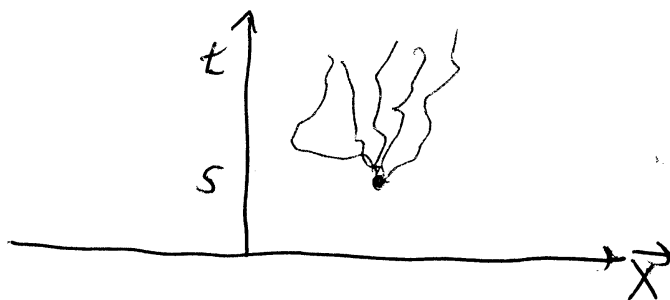
is one way to solve for

$$\begin{aligned} u(\vec{x}, s) &= \mathbb{E} (f(\vec{x} + \vec{W}(t-s))) \\ &= \mathbb{E} (f(\vec{X}(t)) \mid \vec{X}(s) = \vec{x}) \end{aligned}$$

where $\vec{X}(t) = \vec{x} + \vec{W}(t-s)$

$$\vec{W}(t) = \begin{pmatrix} W_1(t) \\ W_2(t) \\ \vdots \\ W_d(t) \end{pmatrix} \quad \text{and each } W_i(t) \text{ is an independent Wiener process}$$

Like a random MOC



For a general diffusion process w/ variable drift and diffusion, one might guess the appropriate diff eqn to write down is:

$$\frac{d\vec{X}}{dt} = \vec{v}(\vec{X}(t), t) + \sigma(\vec{X}(t), t) \frac{d\vec{W}}{dt}$$

↑
↑

drift
diffusivity / volatility

mean trend

But $\frac{d\vec{W}}{dt}$ doesn't exist!

Write instead

$$d\vec{X} = \vec{v}(\vec{X}(t), t) dt + \sigma(\vec{X}(t), t) d\vec{W}(t)$$

Stochastic Differential Equation

There are hidden subtlety in the $d\vec{W}$ term.

Examples of SDEs:

- 1) Particle moving through a low Reynolds # fluid w/ thermal fluctuations

$$m d\vec{v} = -\underset{\text{friction}}{\gamma \vec{v}} dt + \underset{\text{thermal}}{\sigma} d\vec{W}$$

\vec{v} = velocity

m = mass

γ = friction constant

σ = noise parameter

Physicist notation (sometimes)

$$m \frac{d\vec{v}}{dt} = -\gamma \vec{v} + \vec{f}_T(t)$$

$\vec{f}_T(t)$ thermal force

$$\langle \vec{f}_T(t) \otimes \vec{f}_T(t') \rangle = \sigma^2 \delta(t-t')$$

$$\langle \vec{f}_T(t) \rangle = 0$$

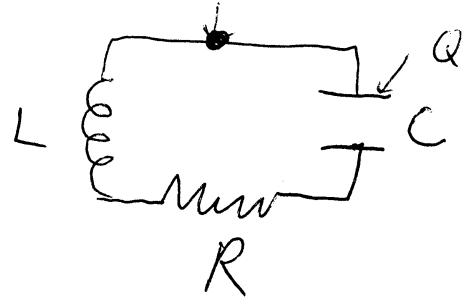
"white noise"

- 2) Particle with added external potential $U(\vec{x})$

$$d\vec{x} = \vec{v} dt$$

$$m d\vec{v} = -\underset{\text{friction}}{\gamma \vec{v}} dt - \underset{\text{force from potential}}{\vec{\nabla} U(\vec{x})} dt + \underset{\text{thermal}}{\sigma} d\vec{W}(t)$$

3) LRC circuit

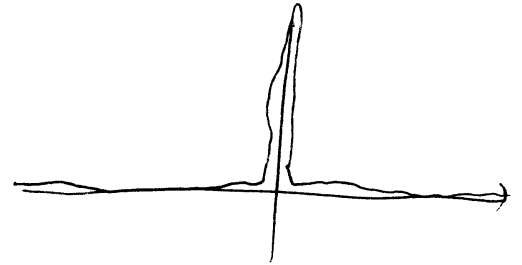


$$L \frac{d^2 Q}{dt^2} + R \frac{dQ}{dt} + \frac{Q}{C} = V_{\text{ext}}(t) + \tilde{V}(t)$$

Q = charge on capacitor

V_{ext} = applied voltage

\tilde{V} = thermal flux



"White noise" fluctuations: $\langle \tilde{V}(t) \tilde{V}(t') \rangle = \sigma^2 \delta(t-t')$

SDE formalism:

$$dQ = I dt$$

$$L dI + R I dt + C Q dt = \sigma dW(t) + V_{\text{ext}}(t) dt$$

4) Turbulent transport

$$d\vec{X} = \vec{u}(\vec{X}(t), t) dt + \sqrt{2K} d\vec{W}(t)$$

$\vec{X}(t)$ = position of a tracer

$\vec{u}(\vec{x}, t)$ = flow of fluid

K is like eddy diffusivity

$$K = K(\vec{x}, t)$$

molecular / unresolved velocity

5) Finance

Black-Scholes model (geometric Brownian motion)

$X(t)$ = asset price

$$dX = \mu X dt + \sigma X dW(t)$$

mean rate of growth = μ

volatility is proportional to current price

6) Stochastic filtering (Oksendal)

Model for how to interpret

noisy measurements of an unpredictable system.

unpredictability



System Model

$$dX = b(t, X(t)) dt + \sigma(t, X(t)) dW_1(t)$$

Observation Model

$$dZ = c(t, X(t)) dt + \underbrace{\delta(t, X(t)) dW_2(t)}_{\text{error in measurements}}$$

$dW_1(t)$ and $dW_2(t)$ are independent

General principle:

The stochastic diff eq (SDE)

$$d\vec{X} = \vec{v}(\vec{X}(t), t) dt + \sigma(\vec{X}(t), t) d\vec{W}(t)$$

with the "Itô" interpretation

generates a Markov process which

is a diffusion process with drift

$$\vec{v}(\vec{x}, t) \text{ and diffusivity } \kappa(\vec{x}, t) = \frac{1}{2} \sigma \sigma^T$$

and infinitesimal generator

$$A = \vec{v}(\vec{x}, t) \cdot \vec{\nabla} + \kappa(\vec{x}, t) : \vec{\nabla} \vec{\nabla}$$

Many questions involving $\vec{X}(t)$ can be solved in terms of PDEs involving A .

For example: i) Prob. trans. densities $p(s, \vec{x}; t, \vec{y})$

$$\text{Kol back: } -\frac{\partial}{\partial s} p = A_{\vec{x}, s} p \quad \text{Kol forw: } \frac{\partial}{\partial t} p = A_{\vec{y}, t}^* p$$

ii) Suppose that I accumulate a cost/reward at a rate $f(\vec{x})$ where $\vec{x} \in S$,

$$\vec{w}(\vec{x}, t) = \mathbb{E} \left[\int_0^t f(\vec{X}(s)) ds \mid \vec{X}(0) = \vec{x} \right]$$

Accumulated cost/reward up to time t ,
given initial state \vec{x} ,

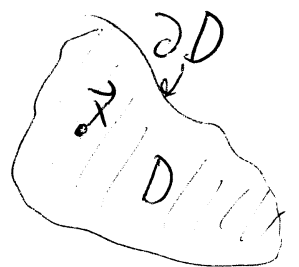
This is the solution to parabolic PDE:

$$\frac{\partial \vec{w}}{\partial t} = A \vec{w} + \vec{f}$$

$$\vec{w}(t=0) = \vec{0}$$

iii) Suppose the state space has a bounded domain D with boundary ∂D

Let τ be first time that $\vec{X}(t)$ hits ∂D ,



Consider

$$\vec{v}(\vec{x}) = \mathbb{E} \left[\int_0^\tau \vec{f}(\vec{X}(s)) ds + \vec{g}(\vec{X}(\tau)) \mid \vec{X}(t=0) = \vec{x} \right]$$

This satisfies elliptic PDE

$$A \vec{v} + \vec{f} = 0 \quad \text{for } \vec{x} \in D$$

$$\vec{v} = \vec{g} \quad \text{for } \vec{x} \in \partial D$$

What's the difficulty with making sense of SDE?

$$d\vec{X} = \vec{v}(\vec{X}(t), t) dt + \sigma(\vec{X}(t), t) d\vec{W}(t)?$$

If I write it in integral form:

$$\vec{X}(t) - \vec{X}(0) = \int_0^t \vec{v}(\vec{X}(s), s) ds + \underbrace{\int_0^t \sigma(\vec{X}(s), s) d\vec{W}(s)}_{\text{How define?}}$$

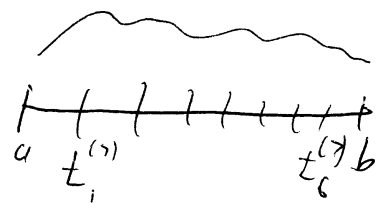
How define?

Lebesgue integration doesn't work because ~~it~~ $\vec{W}(t)$ doesn't have bounded variation.

What about Riemann-Stieltjes interpretation?

Consider an integral like

$$\int_0^b f(W(t), t) dW(t)$$



Define a partition $a = t_0^{(n)} < t_1^{(n)} < \dots < t_n^{(n)} = b$

The Riemann-Stieltjes sum:

$$\sum_{j=1}^n f(W(I_j^{(n)}), I_j^{(n)}) \underbrace{(W(t_j^{(n)}) - W(t_{j-1}^{(n)}))}_{(W(t_j^{(n)}) - W(t_{j-1}^{(n)}))}$$

where $t_{j-1}^{(n)} \leq I_j^{(n)} \leq t_j^{(n)}$ does not give unique answer!