

SMOOTHING

(Nesterov, 2005)

Used for nonsmooth convex problems; $\min f(x)$

approximate by smooth convex problem, $\min f_\mu(x)$
and use ~~sub~~ gradient descent.

Complexity # iterations depends on (L_μ / ϵ_μ)

(linear in this, with correct design of algo)

where L_μ is Lipschitz constant of ∇f_μ

and ϵ_μ is accuracy with which smooth problem is solved.

Trade-off:

Large $L_\mu \leftrightarrow$ less smoothing \Rightarrow more accurate approximation

Small $L_\mu \leftrightarrow$ more smoothing \Rightarrow faster convergence.

Eg:

$$f(x) = \lambda_{\max}(x). \quad \left(\begin{array}{l} \text{Minimize max eval,} \\ \text{subject to some constraints} \end{array} \right)$$

$x \succeq 0.$

Smooth approximation:

$$f_\mu(x) = \mu \log \left(\sum_{i=1}^n e^{\lambda_i(x)/\mu} \right) - \mu \log n.$$

$$\lim_{\mu \rightarrow 0} f_\mu(x) = f(x).$$

$$L_\mu = \frac{1}{\mu}$$