

Strong Duality Theorem

$$X \subseteq \mathbb{R}^n \text{ convex}$$

$$f: \mathbb{R}^n \rightarrow \mathbb{R},$$

$$h: \mathbb{R}^n \rightarrow \mathbb{R}^p$$

$$g: \mathbb{R}^n \rightarrow \mathbb{R}^m$$

convex,

CQ holds:

affine

$$(i.e. h(x) = Ax - b)$$

~~$\exists x \in \text{int } X$~~

$\exists x \in X$

s.t. $g(x) < 0$

$$h(x) = 0; \quad \emptyset$$

$$0 \in \text{int } h(X)$$

$$h(x) = \{y: y \leq h(x) \text{ for some } x \in X\}$$

Then: $\inf \{f(x): x \in X, g(x) \leq 0, h(x) = 0\}$

$$= \sup \{D(u, v): u \geq 0\}$$

Furthermore: if inf is finite then sup is achieved at (\bar{u}, \bar{v})

if inf is achieved at \bar{x} , then $\bar{u}^T g(\bar{x}) = 0$.

Let $\gamma = \inf \{ f(x) : x \in X, g(x) \leq 0, h(x) = 0 \}$.

If $\gamma = -\infty$, result trivial. (Weak duality)

Assume γ finite, let $\alpha(x) := f(x) - \gamma$.

Then the system: $\alpha(x) < 0, g(x) \leq 0, h(x) = 0, x \in X$
has no solution.

$\therefore \exists (u_0, u, v) \neq 0$ satisfying

$$(*) \quad u_0 (f(x) - \gamma) + u^T g(x) + v^T h(x) \geq 0 \quad \forall x \in X,$$

$u_0 \geq 0, u \geq 0.$

Assume $u_0 = 0$:

By assumption, $\exists \hat{x}$ with $g(\hat{x}) < 0, h(\hat{x}) = 0$.

~~Thus, $u^T g$~~

We need $u^T g(\hat{x}) \geq 0$

$\therefore u = 0$, since $u \geq 0, g(\hat{x}) < 0$

$\therefore v^T h(x) \geq 0 \quad \forall x \in X$

But $0 \in \text{int } h(x)$

$\therefore \exists x$ s.t. $h(x) = -\lambda v$ for some small $\lambda > 0$.

$\therefore v^T v = 0 \quad \therefore v = 0$ ~~to~~ $(u_0, u, v) \neq 0$.

$\therefore u_0 > 0$

Divide (*) by u_0 , write $\bar{u} = \frac{u}{u_0}, \bar{v} = \frac{v}{u_0}$:

$$f(x) + \bar{u}^T g(x) + \bar{v}^T h(x) \geq \gamma \quad \forall x \in X$$

$$\therefore \sup (\theta(u, v) : u \geq 0) \geq \gamma$$

But by weak duality, $\sup (\theta(u, v) : u \geq 0) \leq \gamma$

$$\therefore \sup (\theta(u, v) : u \geq 0) = \gamma,$$

and sup is achieved by \bar{u}, \bar{v} .

If z^* is achieved at \bar{x} :

$$\text{Then } f(\bar{x}) = \gamma, \quad g(\bar{x}) \leq 0, \quad h(\bar{x}) = 0$$

But also,

$$f(\bar{x}) + \bar{u}^T g(\bar{x}) + \bar{v}^T h(\bar{x}) \geq \gamma$$

$$\therefore \bar{u}^T g(\bar{x}) \geq 0$$

$$\therefore \bar{u}^T g(\bar{x}) = 0$$

//.

Geometrically, why do we need $g(x) < 0$ for some x , and

$0 \in \text{int } h(X)$?

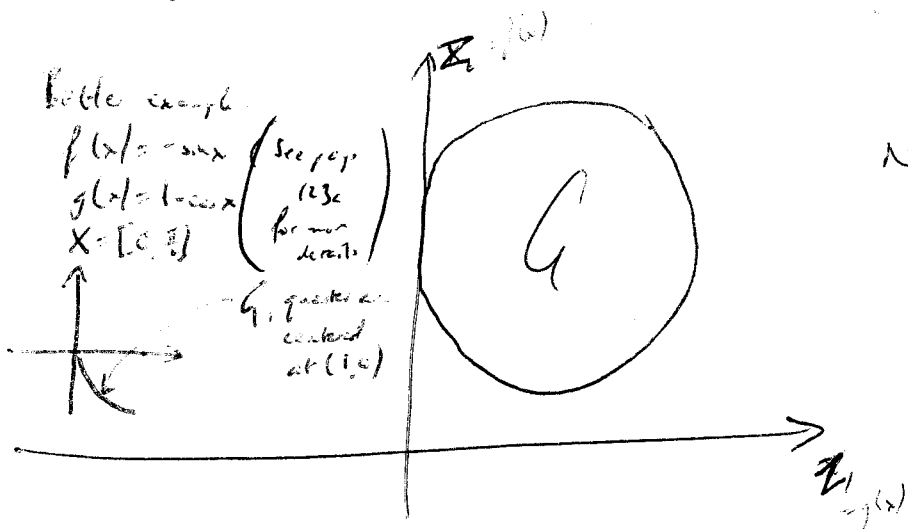
2nd order cone

If $g(x) \neq 0 \forall x \in X$:

Little example

$f(x) = \max$ (See pop 123c for more details)
 $g(x) = 1 - \cos x$
 $X = [0, \pi]$

g is quadratic centered at $(1, 0)$



Could replace this by saying $X = [0, \pi]$

Need to take x_2 axis

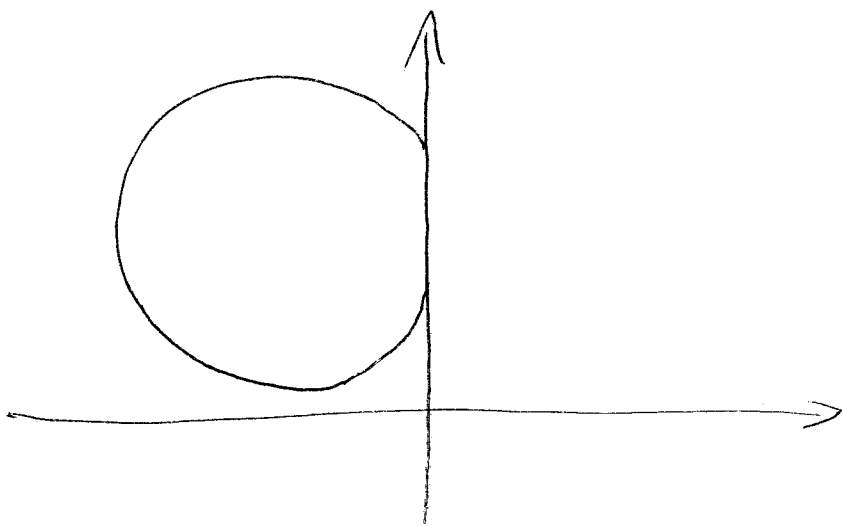
as supporting hyperplane

But this corresponds to

$u = \infty$, so sup is not achieved

achieved

Study if $0 \notin \text{int } h(X)$, then



Same argument works, but

we have $v \rightarrow -\infty$

giving optimal dual solution

What does $0 \in \text{int } h(X)$ mean?

~~$\exists x \in X$~~

$$\forall \bar{x}, \bar{y} \in X \quad \forall \alpha \in \mathbb{R} \quad A\bar{x} \leq b \leq A\bar{y}$$

If $X = \mathbb{R}^n$:

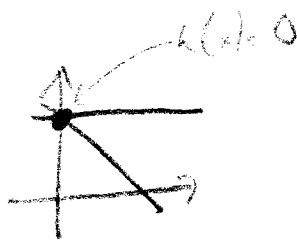
$$\text{Let } y \in \mathbb{R}^m,$$

$$\text{Let } x = A^T(AA^T)^{-1}(y+b)$$

$$\text{Then } Ax - b = (y+b) - b = y$$

So for any $y \in \mathbb{R}^m$, $\exists x \in X$ s.t. $h(x) = y$.

$$\therefore 0 \in \text{int } h(X).$$



If $X = \mathbb{R}_+^2$:

$0 \notin \text{int } h(X)$ roughly corresponds to the existence of a dependent obj.

$$\text{Eg. } h(x) = \begin{pmatrix} x_1 + x_2 - 4 \\ x_2 - 2 \end{pmatrix} \quad x \in \mathbb{R}_+^2, \quad 0 = h\left(\begin{pmatrix} 0 \\ 2 \end{pmatrix}\right)$$

$$\text{Then } 0 \notin \text{int } h(X) \quad \begin{pmatrix} \epsilon \\ \epsilon \end{pmatrix} \notin h(X) \text{ for any } \epsilon > 0 \quad \begin{pmatrix} \epsilon \\ \epsilon \end{pmatrix} = h\left(\begin{pmatrix} -\epsilon \\ 2-\epsilon \end{pmatrix}\right) \\ \begin{pmatrix} -\epsilon \\ 0 \end{pmatrix} \notin h(X) \text{ for any } \epsilon > 0 \quad \begin{pmatrix} -\epsilon \\ 0 \end{pmatrix} = h\left(\begin{pmatrix} -\epsilon \\ 2 \end{pmatrix}\right)$$

$$\text{If } h(x) = \begin{pmatrix} -x_1 - 2 \\ x_2 - 1 \end{pmatrix} \quad x \in \mathbb{R}_+^2$$

$$\text{Then } 0 \in \text{int } h(X) \quad 0 = h\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}\right)$$

$$\begin{aligned} \text{max } & -\sin x \\ \text{s.t. } & (-\cos x) \leq 0 \\ & x \in [0, \frac{\pi}{2}] \end{aligned}$$

$$z_1 = 1 - \cos x, \quad z_2 = -\sin x,$$

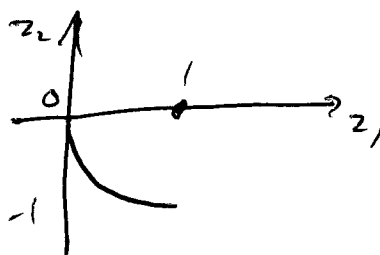
$$\text{so } (z_1 - 1)^2 + z_2^2 = 1$$

$$x=0 \text{ gives } z = (0, 0)$$

$$x = \frac{\pi}{2} \text{ gives } z = (1, 1)$$

Optimal: $x = \frac{\pi}{2}$, value = -1.

This is only feasible solution.



Dual:

$$L(x, u) = -\sin x + u(1 - \cos x)$$

$$\frac{d}{dx} L(x, u) = -\cos x + u \sin x, \quad \text{so } \begin{cases} u \tan x = 1 & \text{if } u > 0 \\ \cos x = 0 & \text{if } u = 0 \end{cases}$$

$$\text{sup } \theta(u) = 0, \quad \text{but } \theta(u) < 0 \quad \forall u \geq 0.$$