

Example:

$$\min \quad x_1^2 + 3x_2$$

$$-x_1 - x_2 + 1 \leq 0$$

$$x_1, x_2 \geq 0.$$

$$(0, x_2) \rightarrow (1-x_2, 3x_2)$$

$$(x_1, 0) \rightarrow (1-x_1, x_1^2)$$

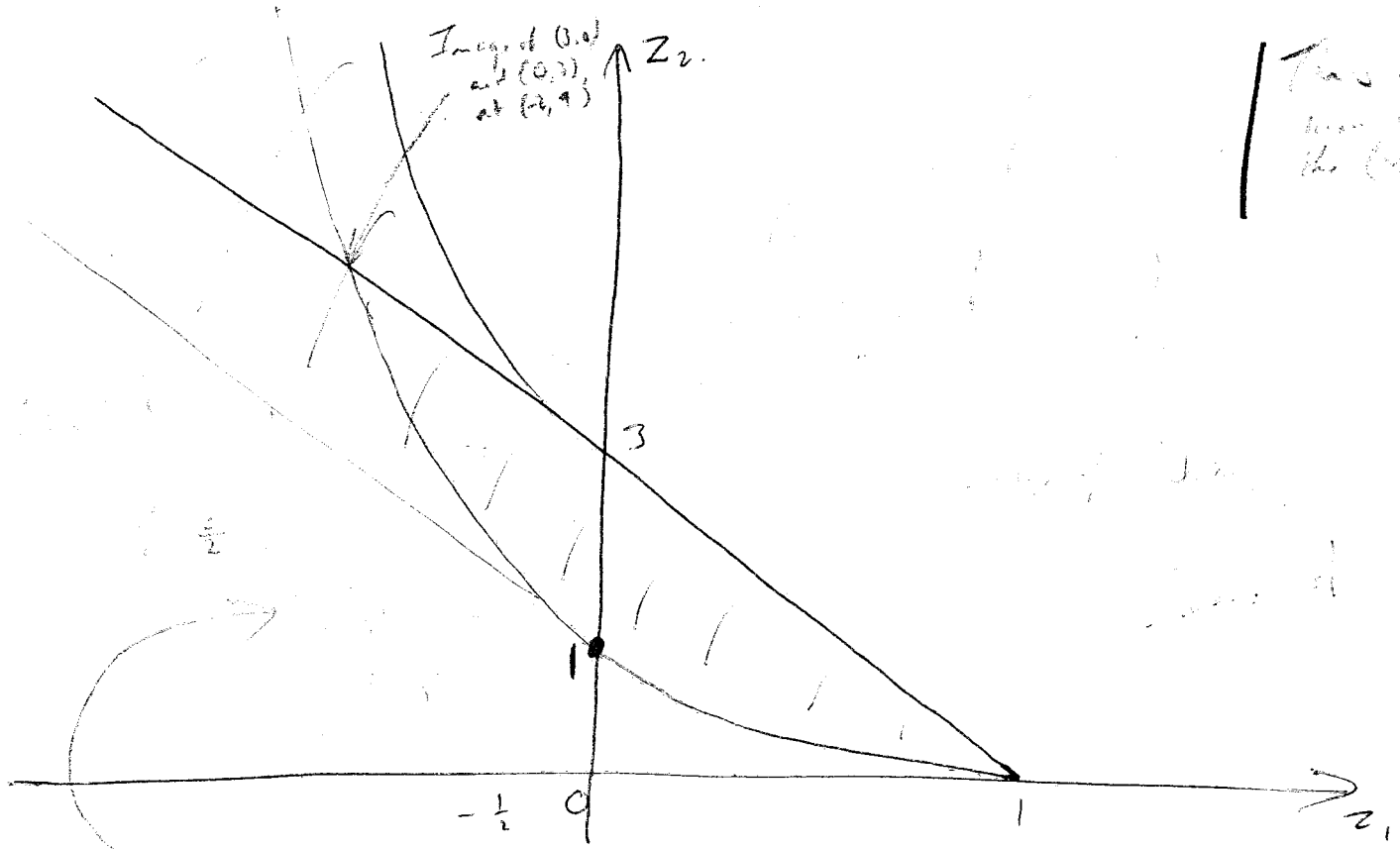


Image of  $\partial(u)$   
at  $(0,3)$   
at  $(2,1)$

This curve  
has 16. Been  
the (optimal) case

$\partial(3)$  gives optimal.

$\partial(u)$  crosses between 0 and 1 if  $u \leq 3$   
crosses at  $-\infty$  if  $u > 3$

## Eg of Lagrangian Duality

$$\max f(x) := x_1^2 + 3x_2$$

$$\text{s.t. } g(x) := -x_1 - x_2 + 1 \leq 0$$

$$x \in X = \{x_1 \geq 0, x_2 \geq 0\}.$$

$$\begin{aligned} \text{Lagrangian is } L(x, u) &= x_1^2 + 3x_2 + u(-x_1 - x_2 + 1) \\ &= (x_1^2 - ux_1) + (3-u)x_2 + u \end{aligned}$$

To find  $\theta(u)$ , we need to solve the problem

$$\min_{x \in X} L(x, u) \quad \begin{array}{l} L \text{ is convex, and } X \text{ is convex.} \\ \text{Thus, any turning point is a local min.} \end{array}$$

$$\text{Now, } \frac{\partial L}{\partial x_1} = 2x_1 - u, \text{ so want } x_1 = \frac{1}{2}u$$

$$\text{and } \frac{\partial L}{\partial x_2} = 3 - u, \text{ so if } \begin{array}{l} u > 3, \text{ get } \theta(u) = -\infty \\ u < 3, \text{ take } x_2 = 0 \\ u = 3, \text{ take } x_2 = \text{anything.} \end{array}$$

$$\begin{aligned} \text{Thus, } \theta(u) &= \begin{cases} +\frac{1}{4}u^2 - \frac{1}{2}u^2 + u & \text{if } u \leq 3 \\ -\infty & \text{if } u > 3 \end{cases} \\ &= \begin{cases} u - \frac{1}{4}u^2 & \text{if } u \leq 3 \\ -\infty & \text{if } u > 3. \end{cases} \end{aligned}$$

$$\text{Maximized when } \bar{u} = 2, \text{ with } \theta(\bar{u}) = 1.$$

$$\text{Corresponding } x \text{ is } \bar{x}_1 = \frac{1}{2}\bar{u} = 1, \bar{x}_2 = 0.$$

Note that  $g(\bar{x}) = 0$ , and  $f(\bar{x}) = 1$ , so by weak duality,  $\bar{x}$  is optimal.

- Then

$$L(\bar{x}, \bar{u}) = \bar{x}_1^2 + 3\bar{x}_2 + \bar{u}(-\bar{x}_1 - \bar{x}_2 + 1) = 1.$$

if

$$x \geq 0,$$

$$L(x, \bar{u}) = x_1^2 + 3x_2 + 2(-x_1 - x_2 + 1)$$

$$= x_1^2 - 2x_1 + x_2 + 2$$

$$\geq -1 + 0 + 2 = 1 = L(\bar{x}, \bar{u})$$

if

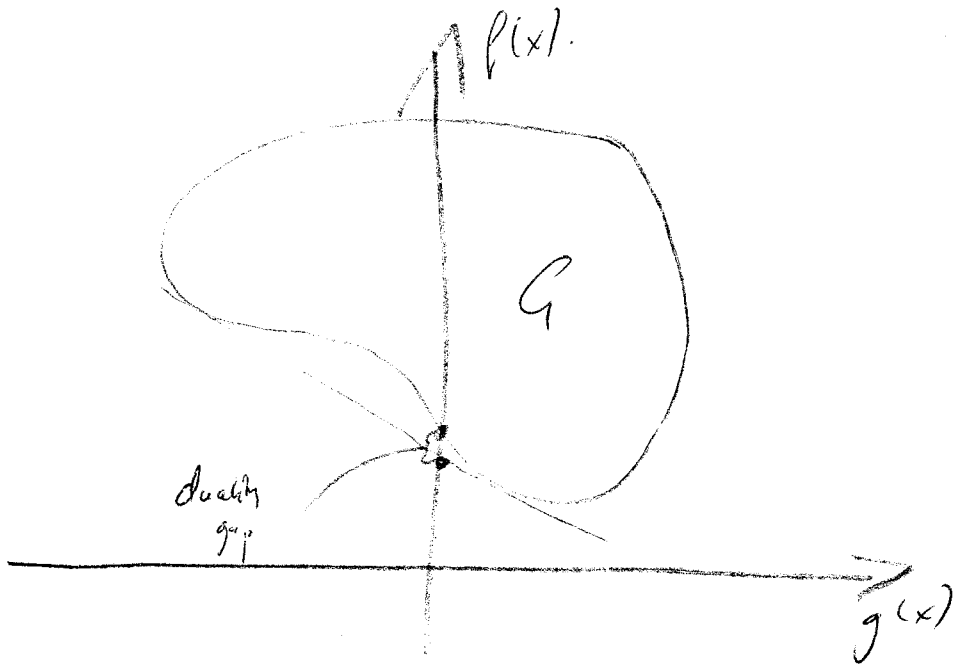
$$u \geq 0:$$

$$L(\bar{x}, u) = 1 + u(0) = 1 \leq L(\bar{x}, \bar{u}).$$

So  $\bar{x}, \bar{u}$  is a saddle point.

# Duality gap

Gap between optimal primal and optimal dual values.

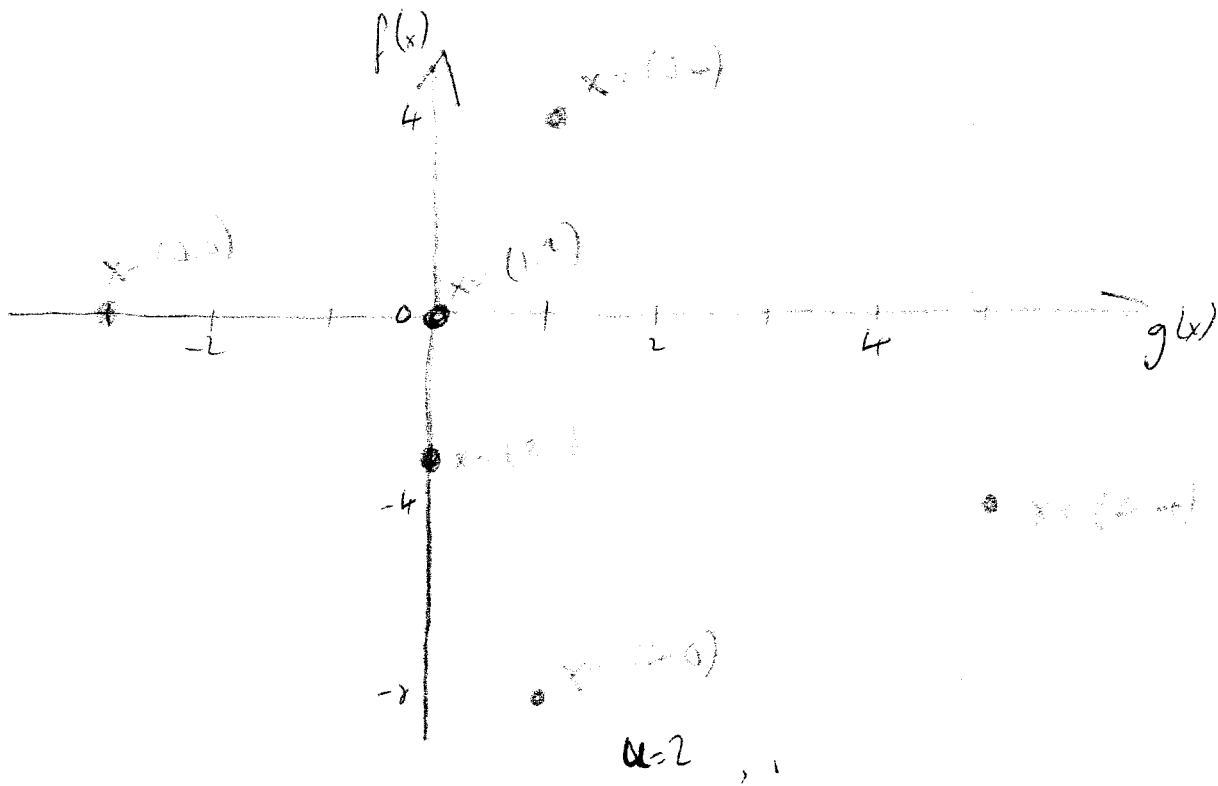


Example with a duality gap:

$$\begin{aligned} \text{Minimize} \quad & -2x_1 + x_2 \\ & x_1 + x_2 - 3 \leq 0 \\ & (x_1, x_2) \in X \end{aligned}$$

$$\text{where } X = \{(0, 0), (0, 4), (4, 4), (4, 0), (1, 2), (2, 1)\}.$$

$f(x) = -2x_1 + x_2$	0	4	-4	-8	0	-3
$g(x) = x_1 - x_2 - 3$	-3	1	5	1	0	0
	(0, 0)	(0, 4)	(4, 4)	(4, 0)	(1, 2)	(2, 1)



$$\theta(u) = \begin{cases} -4 + 5u & u \leq -1 \\ -8 + u & -1 < u \leq 2 \\ -3u & 2 \leq u \end{cases}$$

Dual value = -6.

Primal value = -3. - achieved by (2, 1).

Weak conditions on Slater duality gap is zero.

First need the Lemma:

Lemma  $X \subseteq \mathbb{R}^n$ , convex,  $X \neq \emptyset$ .

$\alpha: \mathbb{R}^n \rightarrow \mathbb{R}$ ,  $g: \mathbb{R}^n \rightarrow \mathbb{R}^m$  convex

$h: \mathbb{R}^n \rightarrow \mathbb{R}^p$  affine, ie  $h(x) = Ax - b$ .

System 1:  $\alpha(x) < 0$ ,  $g(x) \leq 0$ ,  $h(x) = 0$  for some  $x \in X$

System 2:  $u_0 \alpha(x) + u^T g(x) + v^T h(x) \geq 0$  for all  $x \in X$   
 $(u_0, u) \geq 0$ ,  $(u_0, u, v) \neq 0$

If System 1 has no solution  $x$ , then System 2 has a solution  $(u_0, u, v)$ . The converse holds, if  $u_0 > 0$ .

Proof Suppose System 1 has no solution.

Define  $\Lambda = \{(p, q, r) : p > \alpha(x), q \geq g(x), r = h(x) \text{ for some } x \in X$

$\Lambda$  is convex (exercise)

System 1 has no solution.  $\therefore (0, 0, 0) \notin \Lambda$

$\therefore \exists$  separating hyperplane separating  $(0, 0, 0)$  from  $\text{cl } \Lambda$ , ie  $\exists u_0, u, v$  not all zero  
st.  $u_0 p + u^T q + v^T r \geq 0 \quad \forall (p, q, r) \in \text{cl } \Lambda$

Fix an  $x \in X$ . Then  $p$  &  $q$  can be made arbitrarily large.

$\therefore (u_0, u) \geq 0$ . Also,  $\{(p, q, r) = [\alpha(x), g(x), h(x)]$  belongs to  $\text{cl } \Lambda$ .

~~Therefore~~ The result follows.

weser:

Assume System 2 has a solution with  $u_0 > 0$ :

If  $x \in X$  with  $g(x) \leq 0, h(x) = 0$  then

$$u_0 \alpha(x) \geq 0 \quad \text{since} \quad u \geq 0$$

Thus  $\alpha(x) \geq 0$ , so System 1 has no solution.