

Differentiable convex functions

$$S \subseteq \mathbb{R}^n, \quad f: S \rightarrow \mathbb{R}.$$

f is said to be differentiable at $\bar{x} \in \text{int} S$ if there exists a vector $\nabla f(\bar{x})$, called the gradient vector, and a function $\alpha: \mathbb{R}^n \rightarrow \mathbb{R}$ such that

$$f(x) = f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x}) + \|x - \bar{x}\| \alpha(\bar{x}; x - \bar{x})$$

~~for each~~ $x \in S$ $\forall x \in S,$

where $\lim_{x \rightarrow \bar{x}} \alpha(\bar{x}, x - \bar{x}) = 0$.

f is differentiable on ~~the~~ the open set $S' \subseteq S$ if it is differentiable at each point in S' .

If f is differentiable,

$$\nabla f(\bar{x}) = \left(\frac{\partial f(\bar{x})}{\partial x_1}, \dots, \frac{\partial f(\bar{x})}{\partial x_n} \right)^T.$$

Theorem Let $S \subset \mathbb{R}^n$ be a nonempty open convex set in \mathbb{R}^n .
 Let $f: C \rightarrow \mathbb{R}$ be diff. on C .

Then f is convex if and only if for any $\bar{x} \in S$,

$$f(x) \geq f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x}).$$

Proof Follows from Lemma and Theorems. [NB: Useful in, e.g., Golub & Van der Veen's approach to convex optimization.

Theorem $C \subset \mathbb{R}^n$ nonempty, convex, open. $f: C \rightarrow \mathbb{R}$ diff. on C .

Then f is convex if and only if

$$\forall x_1, x_2 \in S \implies [\nabla f(x_2) - \nabla f(x_1)]^T (x_2 - x_1) \geq 0.$$

Proof. \implies Assume f convex. Let $x_1, x_2 \in S$

Skip this if do proof on p 41 (a) of previous theorem

So $f(x_2) \geq f(x_1) + \nabla f(x_1)^T (x_2 - x_1)$

$f(x_1) \geq f(x_2) + \nabla f(x_2)^T (x_1 - x_2)$

Adding: $[\nabla f(x_2) - \nabla f(x_1)]^T (x_2 - x_1) \geq 0$

\Leftarrow Assume $\forall x_1, x_2 \in S \implies [\nabla f(x_2) - \nabla f(x_1)]^T (x_2 - x_1) \geq 0 \forall a, b \in S$

Let $x_1, x_2 \in S$.

By MVT, there is some $x = \lambda x_1 + (1-\lambda)x_2$ ($0 \leq \lambda \leq 1$) s.t.

$$\nabla f(x)^T (x_2 - x_1) = f(x_2) - f(x_1).$$

Proof of First theorem without using subgradients:

→ Assume f is convex. Thus, the expression $\frac{f(\bar{x} + \lambda d) - f(\bar{x})}{\lambda}$ is monotonically increasing in λ , and

$$\frac{f(\bar{x} + \lambda d) - f(\bar{x})}{\lambda} \geq \lim_{\lambda \rightarrow 0^+} \frac{f(\bar{x} + \lambda d) - f(\bar{x})}{\lambda} = \nabla f(\bar{x})^T d$$

⇐ Assume f is not convex:

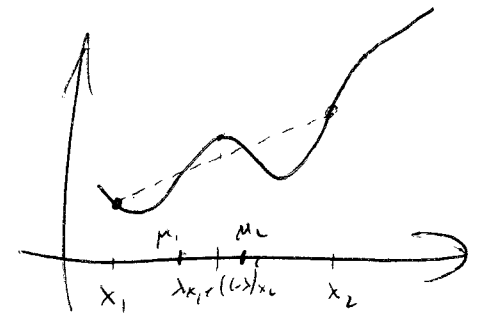
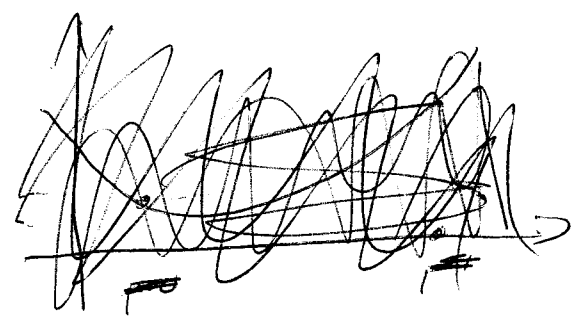
So $\exists x_1, x_2, \lambda, 0 < \lambda < 1$ with $f(\lambda x_1 + (1-\lambda)x_2) > \lambda f(x_1) + (1-\lambda)f(x_2)$

Consider an interval ~~$[x_3, x_4] \subseteq [x_1, x_2]$~~ with

~~$f(x_3)$~~ $[\mu_1, \mu_2] \subseteq [0, 1]$, with

- (i) $\mu_1 \neq \mu_2$
- (ii) $f(\mu_1 x_1 + (1-\mu_1)x_2) = \mu_1 f(x_1) + (1-\mu_1)f(x_2)$
- (iii) $f(\mu_2 x_1 + (1-\mu_2)x_2) = \mu_2 f(x_1) + (1-\mu_2)f(x_2)$
- (iv) $f(\mu x_1 + (1-\mu)x_2) \geq \mu f(x_1) + (1-\mu)f(x_2), \mu_1 \leq \mu \leq \mu_2$

Because λ exists, such an interval in μ must exist.



Don't need mu. Could jump from x3.

Then $\exists \hat{\mu} \in [\mu_1, \mu_2]$ with $\nabla f(\hat{\mu} x_1 + (1-\hat{\mu})x_2)^T (x_2 - x_1) = f(x_2) - f(x_1)$
 $= \frac{f(x_2) - f(x_1)}{x_2 - x_1} \cdot (x_2 - x_1) = f(x_2) - f(x_1)$
 Then $\nabla f(x_3)^T (x_3 - x_1) \leq f(x_3) - f(x_1)$, or $f(x_1) < f(x_3) + \nabla f(x_3)^T (x_1 - x_3)$ QED

By assumption, $[\nabla f(x) - \nabla f(x_1)]^T (x - x_1) \geq 0$

$$\Rightarrow [\nabla f(x) - \nabla f(x_1)]^T (x_2 - x_1) \geq 0$$

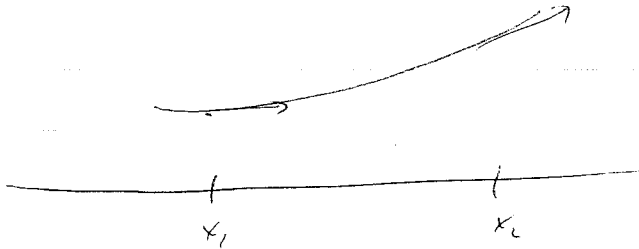
since $x_2 - x_1$ is parallel to $x - x_1$.

$$\therefore \nabla f(x)^T (x_2 - x_1) \geq \nabla f(x_1)^T (x_2 - x_1)$$

$$\therefore f(x_2) - f(x_1) \geq \nabla f(x_1)^T (x_2 - x_1)$$

$$\therefore f(x_2) \geq f(x_1) + \nabla f(x_1)^T (x_2 - x_1) \quad //$$

This last theorem looks sort of second order,
with differences in derivatives: as you move from x_1
to x_2 , the ^{component of the} derivative in that direction increases.



Twice differentiable convex fns

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Defn $f: S \subseteq \mathbb{R}^n$, nonempty. $f: S \rightarrow \mathbb{R}$

f is twice differentiable on subset of \mathbb{R}^n

\iff at $\bar{x} \in \text{int } S$ if there exists a vector $\nabla f(\bar{x})$,
the gradient vector, and an $n \times n$ matrix $\nabla^2 f(\bar{x})$ (or $H(\bar{x})$),

the Hessian matrix, and a function $\alpha(\bar{x}; x - \bar{x})$ such that

$$f(x) = f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x}) + \frac{1}{2} (x - \bar{x})^T \nabla^2 f(\bar{x}) (x - \bar{x}) \\ + \|x - \bar{x}\|^2 \alpha(\bar{x}; x - \bar{x}), \quad \forall x \in S$$

where $\lim_{x \rightarrow \bar{x}} \alpha(\bar{x}; x - \bar{x}) = 0$.

f is twice differentiable on open set $S' \subseteq S$ if it is twice
differentiable at each point in S' . (also called smooth, C^2)

(i, j) th component of $\nabla^2 f(\bar{x})$ is $\frac{\partial^2 f}{\partial x_i \partial x_j}(\bar{x})$.

Thm $C \subseteq \mathbb{R}^n$ open, convex, nonempty $f: C \rightarrow \mathbb{R}$, twice differentiable. f is convex on $C \iff H$ is p.s.d. on C .Pf $\Rightarrow f$ convex:Take $\bar{x} \in S$ Need to show $d^T H f(\bar{x}) d \geq 0 \quad \forall d \in \mathbb{R}^n$. $\bar{x} + \lambda d \in S$ for λ small enough for any d . $\therefore f(\bar{x} + \lambda d) \geq f(\bar{x}) + \lambda \nabla f(\bar{x})^T d$, since f convex.

$$\text{Also } f(\bar{x} + \lambda d) = f(\bar{x}) + \lambda \nabla f(\bar{x})^T d + \lambda^2 d^T \nabla^2 f(\bar{x})^T d + \lambda^3 \|\nabla^3 f(\bar{x})\| \lambda d$$

$$\text{So } \lambda^2 d^T \nabla^2 f(\bar{x})^T d + \lambda^3 \|\nabla^3 f(\bar{x})\| \lambda d \geq 0$$

Cancel λ^2 .Take limit as $\lambda \rightarrow 0$:

$$d^T \nabla^2 f(\bar{x})^T d \geq 0.$$

 $\Leftarrow H$ is psd on C .Given $x, \bar{x} \in C$ By ~~MVT~~ ^{MVT}, we have ~~some~~ $\hat{x} = \lambda \bar{x} + (1-\lambda)x$ for some $\lambda \in (0,1)$.

satisfying

$$f(x) = f(\bar{x}) + \nabla f(\bar{x})^T (x - \bar{x}) + \frac{1}{2} (x - \bar{x})^T H(\hat{x}) (x - \bar{x}).$$

~~$$\text{for some } \hat{x} \in C(x, \bar{x}).$$~~

Characterizations of positive definiteness

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 2x2 = x^T M x
 = x^T (a b; b c) x
 = a x^2 + 2 b x y + c y^2
 So positive definite means
 a > 0, c > 0, ac > b^2

Consider matrix M

By defn., M is positive definite if $x^T M x > 0 \quad \forall x \in \mathbb{R}^n, x \neq 0$

Equivalent to saying all eigenvalues of M are positive.

Also:

M p.d. \Rightarrow All principal subdeterminants are positive

M p.d. $\Rightarrow \exists$ factorization LDU where L lower tri,
 U upper tri, diagonal entries 1, D positive diagonal entries.

If M is symmetric:

M p.d. $\Leftrightarrow \exists$ Cholesky factorization $M = LL^T$, where
 all diagonal entries of L are +ve.

M p.d. \Leftrightarrow All ^{leading} principal subdeterminants are positive.

M psd \Leftrightarrow All principal subdeterminants are nonnegative.

Consider a real trace of $\begin{pmatrix} 1 & 5 \\ -25 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 25 & 26 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 5 \\ 0 & 1 \end{pmatrix}$

$\begin{vmatrix} 1 & 5 \\ -25 & 1 \end{vmatrix} = 26$

Search

is shown in GeVL, p 86, for later use det(A) = det(A^T) (see)

$\bar{x} \in S$, so $H(\bar{x})$ is psd, so $(x - \bar{x})^T H(\bar{x})(x - \bar{x}) \geq 0$

$$\therefore f(x) \geq f(\bar{x}) + Df(\bar{x})^T(x - \bar{x}) \quad //$$

Useful for checking ^{convexity} ~~convexity~~ of a C^2 function.

If f quadratic, $H(x) \equiv H$, so only need to check if one matrix is psd.

eg: $f(x) = 3x_1^2 + x_2^2 + 2x_1x_2$

$$= \frac{1}{2} (x_1, x_2) \begin{pmatrix} 6 & 2 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$H(x) = D^2 f(x) = \begin{pmatrix} 6 & 1 \\ 1 & 2 \end{pmatrix} \quad \forall x \in \mathbb{R}^2.$$

Eigenvalues of H are $4 \pm \sqrt{5} > 0$, so p.d.

Defn: ~~f is strictly convex if~~
 $C \subseteq \mathbb{R}^n$ convex, nonempty. $f: C \rightarrow \mathbb{R}$.

f is strictly convex if ~~$x_1, x_2 \in C$~~ ~~$x_1 \neq x_2$~~ , ~~$\lambda \in (0, 1)$~~

~~$$f(\lambda x_1 + (1-\lambda)x_2) > \lambda f(x_1) + (1-\lambda)f(x_2)$$~~

$$x_1 \in C$$

$$x_2 \in C$$

$$\lambda \in (0, 1)$$

$$x_1 \neq x_2$$

$$\Rightarrow f(\lambda x_1 + (1-\lambda)x_2) < \lambda f(x_1) + (1-\lambda)f(x_2)$$